

# Infinite-dimensional $\alpha$ -divergence minimisation for Variational Inference

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Variational Inference Seminar  
24/11/2020

*Joint work with Randal Douc and François Portier*



# Introduction

Goal : build an iterative scheme

$$\mu_{n+1} = \mathcal{I}_\alpha(\mu_n) , \quad n \in \mathbb{N}^* ,$$

- which extends the commonly-used variational approximating family (Infinite-dimensional Variational Inference),
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- ① Background
- ② The  $(\alpha, \Gamma)$ -descent
- ③ Numerical Experiments
- ④ Take-away message
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# Variational Inference in a nutshell

- Bayesian statistics : compute / sample from the **posterior density** of the latent variables  $y$  given the data  $\mathcal{D}$

$$p(y|\mathcal{D}) = \frac{p(\mathcal{D}, y)}{p(\mathcal{D})} .$$

Problem : for many important models, we can only evaluate  $p(y|\mathcal{D})$  up to the constant  $p(\mathcal{D})$ .

→ Variational Inference : inference is seen as an **optimisation problem**.

- ① Posit a variational family  $q$ , where  $q \in \mathcal{Q}$ .
- ② Fit  $q$  to obtain the best approximation to the posterior density

$$q^* = \operatorname{arginf}_{q \in \mathcal{Q}} D(\mathbb{Q} || \mathbb{P}) ,$$

where  $D$  is the a divergence (e.g the Kullback-Leibler).

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# Variational Inference within the $\alpha$ -divergence family (1)

$(Y, \mathcal{Y}, \nu)$  : measured space,  $\nu$  is a  $\sigma$ -finite measure on  $(Y, \mathcal{Y})$ .

$\mathbb{Q}$  and  $\mathbb{P}$  :  $\mathbb{Q} \preceq \nu$ ,  $\mathbb{P} \preceq \nu$  with  $\frac{d\mathbb{Q}}{d\nu} = q$ ,  $\frac{d\mathbb{P}}{d\nu} = p(\cdot | \mathcal{D})$ .

$\alpha$ -divergence between  $\mathbb{Q}$  and  $\mathbb{P}$

$$D_\alpha(\mathbb{Q} || \mathbb{P}) = \int_Y f_\alpha \left( \frac{q(y)}{p(y|\mathcal{D})} \right) p(y|\mathcal{D}) \nu(dy),$$

where

$$f_\alpha = \begin{cases} \frac{1}{\alpha(\alpha-1)} [u^\alpha - 1 - \alpha(u-1)], & \text{if } \alpha \in \mathbb{R} \setminus \{0, 1\}, \\ 1 - u + u \log(u), & \text{if } \alpha = 1 \text{ (Forward KL),} \\ u - 1 - \log(u), & \text{if } \alpha = 0 \text{ (Reverse KL).} \end{cases}$$

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## $\alpha$ -divergence between $\mathbb{Q}$ and $\mathbb{P}$

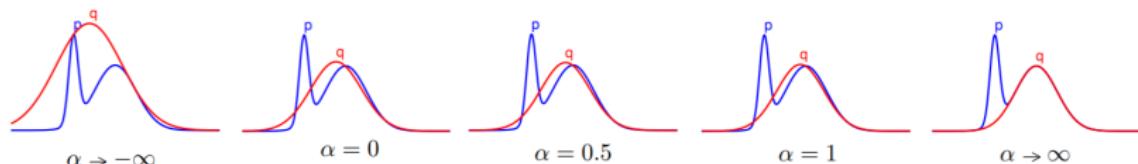
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- ① A **flexible** family of divergences...

**Figure:** The Gaussian  $q$  which minimizes  $\alpha$ -divergence to  $p$  (a mixture of two Gaussian), for varying  $\alpha$



[Adapted from T. Minka (2005) Divergence Measures and Message Passing. Technical Report MSR-TR-2005-173]

# Variational Inference within the $\alpha$ -divergence family (2)

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$$\{y \mapsto k_\theta(y) : \theta \in \mathcal{T}\} .$$

- Recently : Hierarchical Variational Inference!

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$$\left\{ y \mapsto \int_{\mathcal{T}} q_\phi(\theta) k_\theta(y) d\theta : \phi \in \mathcal{A} \right\} .$$

- What if... we consider a broader approximating family

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$\mathcal{M}$  : subset of  $M_1(\mathcal{T})$ , the set of probability measures on  $(\mathcal{T}, \mathcal{T})$  ?

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# Our approach

- Let us consider the approximating family...

$$\left\{ y \mapsto \int_{\mathcal{T}} \mu(d\theta) k_\theta(y) : \mu \in \mathcal{M} \right\},$$

- and minimise the  $\alpha$ -divergence w.r.t  $\mu$ !

Optimisation problem

- $\mu k(y) = \int_{\mathcal{T}} \mu(d\theta) k(\theta, y)$ , where  $K : (\theta, A) \mapsto \int_A k(\theta, y) \nu(dy)$  is a Markov transition kernel on  $\mathcal{T} \times \mathcal{Y}$  with kernel density  $k$
- $p$  : measurable positive function on  $(\mathcal{Y}, \mathcal{Y})$

$$\operatorname{arginf}_{\mu \in \mathcal{M}} \underbrace{\int_{\mathcal{Y}} f_{\alpha} \left( \frac{\mu k(y)}{p(y)} \right) p(y) \nu(dy)}_{:= \Psi_{\alpha}(\mu)}$$

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# The $(\alpha, \Gamma)$ -descent

## Optimisation problem

$$\operatorname{arginf}_{\mu \in M} \Psi_\alpha(\mu) \quad \text{with} \quad \Psi_\alpha(\mu) := \int_Y f_\alpha \left( \frac{\mu k(y)}{p(y)} \right) p(y) \nu(dy)$$

## Algorithm

Let  $\mu_1 \in M_1(T)$  such that  $\Psi_\alpha(\mu_1) < \infty$ . We define the sequence of probability measures  $(\mu_n)_{n \in \mathbb{N}^*}$  iteratively by

$$\mu_{n+1} = \mathcal{I}_\alpha(\mu_n), \quad n \in \mathbb{N}^*. \quad (1)$$

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### **Algorithm 1:** *Exact $(\alpha, \Gamma)$ -descent one-step transition*

---

- ① Expectation step :  $b_{\mu, \alpha}(\theta) = \int_Y k(\theta, y) f'_\alpha \left( \frac{\mu k(y)}{p(y)} \right) \nu(dy)$
  - ② Iteration step :  $\mathcal{I}_\alpha(\mu)(d\theta) = \frac{\mu(d\theta) \cdot \Gamma(b_{\mu, \alpha}(\theta) + \kappa)}{\mu(\Gamma(b_{\mu, \alpha} + \kappa))}$
-

# Monotonicity

(A1) For all  $(\theta, y) \in T \times Y$ ,  $k(\theta, y) > 0$ ,  $p(y) > 0$  and  
 $\int_Y p(y)\nu(dy) < \infty$ .

(A2) The function  $\Gamma : \text{Dom}_\alpha \rightarrow \mathbb{R}_{>0}$  is decreasing, continuously differentiable and satisfies the inequality

$$[(\alpha - 1)(v - \kappa) + 1] (\log \Gamma)'(v) + 1 \geq 0 .$$

## Theorem 1

Assume (A1) and (A2). Let  $\mu \in M_1(T)$  be such that  $\Psi_\alpha(\mu) < \infty$  and  $\mu(\Gamma(b_{\mu,\alpha} + \kappa)) < \infty$ . Then, the two following assertions hold.

- ① We have  $\Psi_\alpha \circ \mathcal{I}_\alpha(\mu) \leq \Psi_\alpha(\mu)$ .
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## Examples satisfying (A2)

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# Limiting behavior

Table 1: Examples of allowed  $(\Gamma, \kappa)$  in the  $(\alpha, \Gamma)$ -descent

Divergence considered	Possible choice of $(\Gamma, \kappa)$	
Forward KL ( $\alpha = 1$ )	$\Gamma(v) = e^{-\eta v}, \eta \in (0, 1)$	any $\kappa$
$\alpha$ -divergence with $\alpha \in \mathbb{R} \setminus \{1\}$	$\Gamma(v) = e^{-\eta v}, \eta \in (0, \frac{1}{ \alpha - 1  \ b\ _{\infty, \alpha + 1}})$	any $\kappa$
	$\alpha > 1, \Gamma(v) = [(\alpha - 1)v + 1]^{\frac{\eta}{1-\alpha}}, \eta \in (0, 1]$	$\kappa > 0$
	$\alpha < 1, \Gamma(v) = [(\alpha - 1)v + 1]^{\frac{\eta}{1-\alpha}}, \eta \in (0, 1]$	$\kappa \leq 0$

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# Mixture models and $(\alpha, \Gamma)$ -descent

$S_J = \left\{ \boldsymbol{\lambda} = (\lambda_1, \dots, \lambda_J) \in \mathbb{R}^J : \forall j \in \{1, \dots, J\}, \lambda_j \geq 0 \text{ and } \sum_{j=1}^J \lambda_j = 1 \right\}$ .  
Let  $\theta_1, \dots, \theta_J \in \mathcal{T}$  be fixed and denote

$$\mu_{\boldsymbol{\lambda}} = \sum_{j=1}^J \lambda_j \delta_{\theta_j} \quad \text{with} \quad \boldsymbol{\lambda} \in S_J.$$

Then,  $\mu_n = \underbrace{\mathcal{I}_{\alpha} \circ \cdots \circ \mathcal{I}_{\alpha}}_{n \text{ times}}(\mu_{\boldsymbol{\lambda}})$  is of the form  $\mu_n = \sum_{j=1}^J \lambda_{j,n} \delta_{\theta_j}$  with

$$\begin{cases} \lambda_1 = \lambda \\ \lambda_{j,n+1} = \frac{\lambda_{j,n} \Gamma(b_{\mu_n, \alpha}(\theta_j) + \kappa)}{\sum_{i=1}^J \lambda_{i,n} \Gamma(b_{\mu_n, \alpha}(\theta_i) + \kappa)} . \end{cases} \quad (2)$$

- In practice, we will use

$$\hat{b}_{\mu_n, \alpha, M}(\theta_j) = \frac{1}{M} \sum_{m=1}^M \frac{k(\theta_j, Y_{m,n})}{\mu_n k(Y_{m,n})} f'_{\alpha} \left( \frac{\mu_n k(Y_{m,n})}{p(Y_{m,n})} \right),$$

with  $Y_{1,n}, \dots, Y_{M,n}$  drawn independently from  $\mu_n k$ .

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# Numerical Experiments

- Framework

**Kernel:** Gaussian transition kernel  $k_h$  with bandwidth  $h$ .

$$\left\{ y \mapsto \mu_{\lambda} k_h(y) = \sum_{j=1}^J \lambda_j k_h(y - \theta_j) : \lambda \in \mathcal{S}_J, (\theta_j)_{1 \leq j \leq J} \in \mathcal{T}^J \right\}.$$

At time  $t$ ,

- ① **Exploitation step** Optimise  $\lambda$  using the  $(\alpha, \Gamma)$ -descent.
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- Toy example

$$p(y) = Z \times [0.5\mathcal{N}(y; -su_d, \mathbf{I}_d) + 0.5\mathcal{N}(y; su_d, \mathbf{I}_d)], Z = 2, s = 2$$

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# Toy Example : Mirror Descent vs Power Descent

We compare :

- 0.5-Mirror descent :  $\Gamma(v) = e^{-\eta v}$  with  $\alpha = 0.5$ ,
- 0.5-Power descent :  $\Gamma(v) = [(\alpha - 1)v + 1]^{\eta/(1-\alpha)}$  with  $\alpha = 0.5$ .

$J = M = 100$ , initial weights:  $[1/J, \dots, 1/J]$ ,  $N = 10$ ,  $T = 20$ .

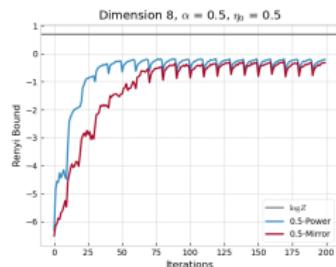
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**Figure:** Average Renyi-Bound for the 0.5-Power and 0.5-Mirror descent computed over 100 replicates with  $\eta_0 = 0.5$ .



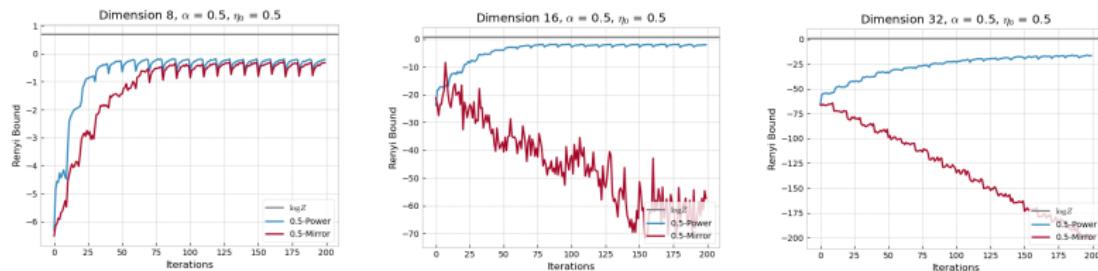
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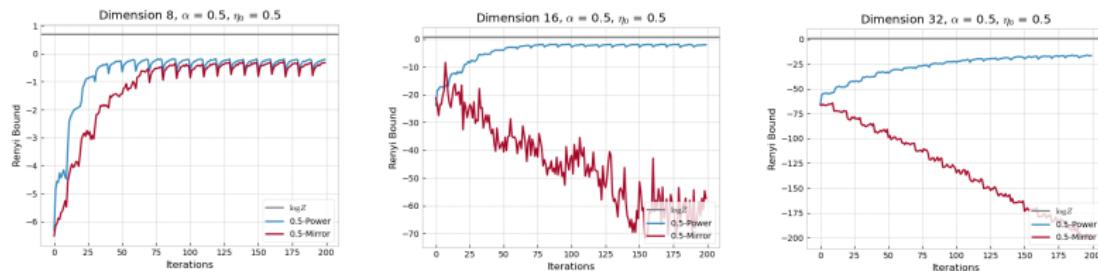
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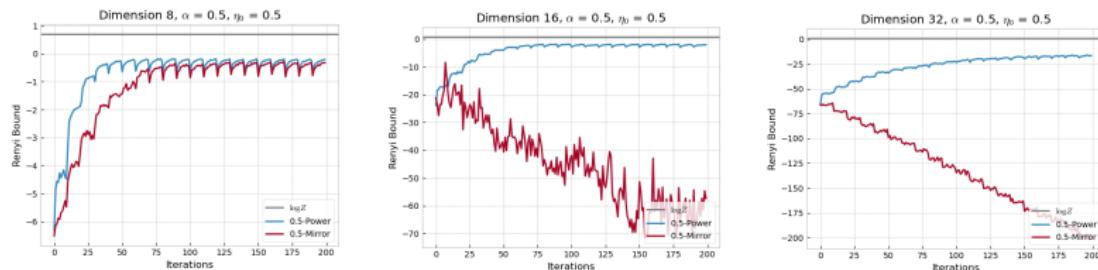
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**Mirror**     $\lambda_{j,n} \propto \exp \left( \frac{\eta}{1-\alpha} \left( (\alpha-1)b_{\mu_{\lambda_n}, \alpha}(\theta_j) + (\alpha-1)\kappa \right) \right)$

**Power**     $\lambda_{j,n} \propto \exp \left( \frac{\eta}{1-\alpha} \log \left( (\alpha-1)b_{\mu_{\lambda_n}, \alpha}(\theta_j) + (\alpha-1)\kappa \right) \right).$

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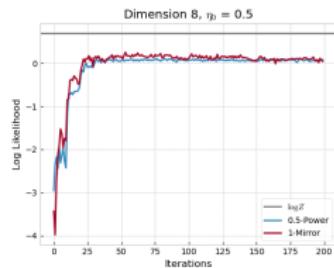
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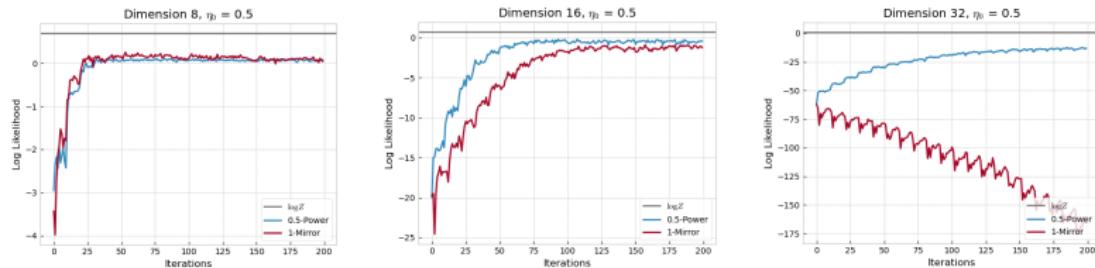


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# Take-away message

## The $(\alpha, \Gamma)$ -descent

- performs an update of probability measures
  - sufficient conditions on  $(\alpha, \Gamma)$  leading to a systematic decrease
  - includes Entropic Mirror Descent
  - convergence to an optimum and  $O(1/N)$  convergence rates,
- can be applied to density approximation
  - handles the case of Mixture Models for any kernel  $K$
  - requires no information on the distribution of  $\{\theta_1, \dots, \theta_J\}$
  - empirical benefit of using the Power descent.

[Kamélia Daudel, Randal Douc and François Portier (2020). Infinite-dimensional gradient-based descent for alpha-divergence minimisation. To be published in the Annals of Statistics. <https://arxiv.org/abs/2005.10618>]

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# The result we want to prove

(A1) For all  $(\theta, y) \in T \times Y$ ,  $k(\theta, y) > 0$ ,  $p(y) > 0$  and  $\int_Y p(y)\nu(dy) < \infty$ .

(A2) The function  $\Gamma : \text{Dom}_\alpha \rightarrow \mathbb{R}_{>0}$  is decreasing, continuously differentiable and satisfies the inequality

$$[(\alpha - 1)(v - \kappa) + 1] (\log \Gamma)'(v) + 1 \geq 0.$$

## Theorem 1

Assume (A1) and (A2). Let  $\mu \in M_1(T)$  be such that  $\Psi_\alpha(\mu) < \infty$  and  $\mu(\Gamma(b_{\mu,\alpha} + \kappa)) < \infty$ . Then, the two following assertions hold.

① We have  $\Psi_\alpha \circ \mathcal{I}_\alpha(\mu) \leq \Psi_\alpha(\mu)$ .

② We have  $\Psi_\alpha \circ \mathcal{I}_\alpha(\mu) = \Psi_\alpha(\mu)$  if and only if  $\mu = \mathcal{I}_\alpha(\mu)$ .

Recall that :

$$\begin{aligned}\Psi_\alpha(\mu) &= \int_Y f_\alpha \left( \frac{\mu k(y)}{p(y)} \right) p(y)\nu(dy) \\ b_{\mu,\alpha}(\theta) &= \int_Y k(\theta, y) f'_\alpha \left( \frac{\mu k(y)}{p(y)} \right) \nu(dy) \\ \mathcal{I}_\alpha(\mu)(d\theta) &= \frac{\mu(d\theta) \cdot \Gamma(b_{\mu,\alpha}(\theta) + \kappa)}{\mu(\Gamma(b_{\mu,\alpha} + \kappa))}\end{aligned}$$

# Step 1 : Proving a general lower bound (1)

Let  $\mu, \zeta \in M_1(T)$  s.t  $\zeta \preceq \mu$  and  $\Psi_\alpha(\mu) < \infty$ . Denote by  $g$  the density of  $\zeta$  w.r.t  $\mu$ .

We have that

$$A_\alpha \leq \Psi_\alpha(\mu) - \Psi_\alpha(\zeta)$$

where  $A_\alpha := \int_Y \nu(dy) \int_T \mu(d\theta) k(\theta, y) f'_\alpha \left( \frac{g(\theta) \mu k(y)}{p(y)} \right) [1 - g(\theta)]$

Equality holds iff  $\zeta = \mu$ .

→ By definition  $\Psi_\alpha(\mu) = \int_Y f_\alpha \left( \frac{\mu k(y)}{p(y)} \right) p(y) \nu(dy)$  with  $f_\alpha$  convex.

→ By convexity of  $f_\alpha$ ,

$$f_\alpha \left( \frac{\mu k(y)}{p(y)} \right) \geq f_\alpha \left( \frac{g(\theta) \mu k(y)}{p(y)} \right) + f'_\alpha \left( \frac{g(\theta) \mu k(y)}{p(y)} \right) \frac{\mu k(y)}{p(y)} [1 - g(\theta)].$$

→ Now integrating first w.r.t to  $\frac{\mu(d\theta)k(\theta,y)}{\mu k(y)}$ ,

$$f_\alpha \left( \frac{\mu k(y)}{p(y)} \right) \geq \int_T \frac{\mu(d\theta)k(\theta,y)}{\mu k(y)} f_\alpha \left( \frac{g(\theta) \mu k(y)}{p(y)} \right) + \int_T \mu(d\theta)k(\theta,y) f'_\alpha \left( \frac{g(\theta) \mu k(y)}{p(y)} \right) \frac{1}{p(y)} [1 - g(\theta)]$$

then w.r.t to  $\nu(dy)p(y)$ , we deduce

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# Step 1 : Proving a general lower bound (1)

Let  $\mu, \zeta \in M_1(T)$  s.t  $\zeta \preceq \mu$  and  $\Psi_\alpha(\mu) < \infty$ . Denote by  $g$  the density of  $\zeta$  w.r.t  $\mu$ .

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Recall that :

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